# TC3MHR096-C

High resolution telecentric lens for 1.1" detectors, magnification 0.153x, C-mount



### SPECIFICATIONS

Magnification

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Image circle Ø	(mm) 17.6	
Object field of view 8	(mm x mm or Ø)	
with IMX174/IMX249 13.3 mm diag w x h 11.35 x 7.13	74.15 x 46.58	
with IMX255/IMX267 16.1 mm diag w x h 14.19 x 7.51	92.75 x 49.08	
with IMX253/IMX304 17.6 mm diag w x h 14.16 x 10.37	92.54 x 67.78	
with KAI-4022/4021 21.5 mm diagonal w x h 15.2 x 15.2	Ø = 99.05	
with KAI-08050 22.6 mm diagonal w x h 18.1 x 13.6 (7)	Ø = 88.86	

(x)

0.153



#### Optical specifications

Working distance (1)	(mm)	278.6
wF/# (2)		8
Telecentricity typical (max) (3)	(deg)	<0.08 (0.10)
Distortion typical (max) (4)	(%)	<0.08 (0.10)
Field depth (5)	(mm)	25.6
CTF@ 50 lp/mm	(%)	> 55

#### Mechanical specifications

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Mount		С
Phase adjustment(9)		Yes
Length (6)	(mm)	354.7
Diameter	(mm)	143
Mass	(g)	2267

## NOTES

- 1. Working distance: distance between the front end of the mechanics and the object. Set this distance within +/- 3% of the nominal value for maximum resolution and minimum distortion.
- 2. Working F-number (wF/#): the real F-number of a lens when used as a macro. Lenses with smaller apertures (higher wF#) can be supplied on request.
- 3. Maximum slope of chief rays inside the lens: when converted to milliradians, it gives the maximum measurement error for any millimeter of object displacement. Typical (average production) values and maximum (guaranteed) values are listed.
- 4. Percent deviation of the real image compared to an ideal, undistorted image: typical (average production) values and maximum (guaranteed) values are listed.
- 5. At the borders of the field depth the image can be still used for measurement but, to get a perfectly sharp image, only half of the nominal field depth should be considered. Pixel size used for calculation is 5.5 µm
- $\,$  6. Measured from the front end of the mechanics to the camera flange.
- 7. With KAI-08050 (22.6 mm diagonal) detectors, the FOV of TC4MHRyyy-x lenses may show some vignetting at the image corners.
- 8. For the fields with the indication "Ø =", the image of a circular object of such diameter is fully inscribed into the detector.
- 9. Indicates the availability of an integrated camera phase adjustment feature